

September 17-20, 2019 Roanoke, Virginia

Assessing the Impact of Data Quality on Pavement Management Systems

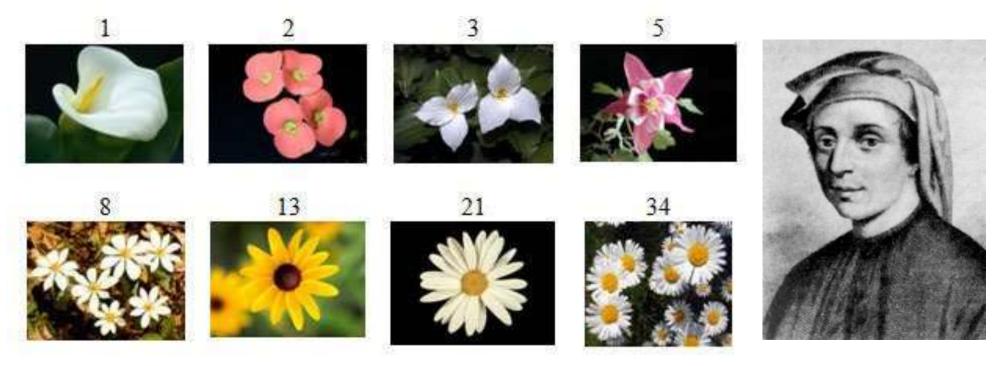
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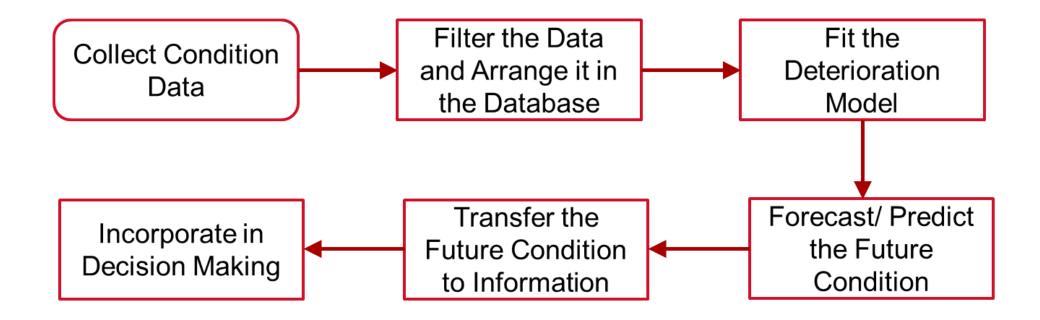
Observe, analyze, model, predict, and decide.



Leonardo Fibonacci 1170 - 1250



From data collection to decision making.





It all starts with monitoring and evaluation inventory.



https://newscenter.nmsu.edu/articles/view/8486

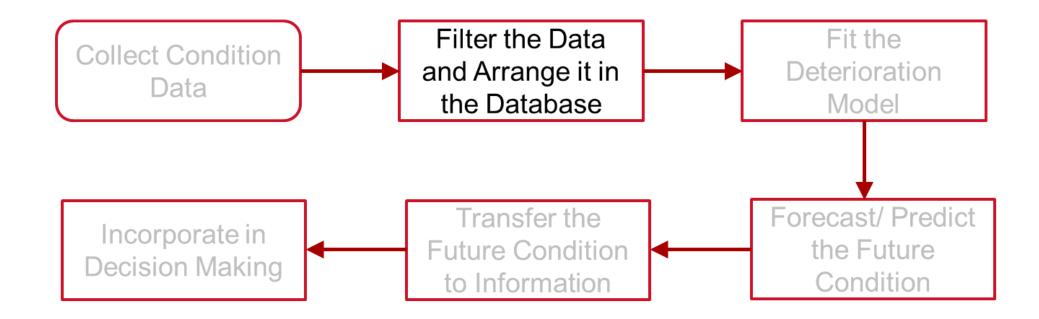


It all starts with monitoring and evaluation inventory.





From data collection to decision making.



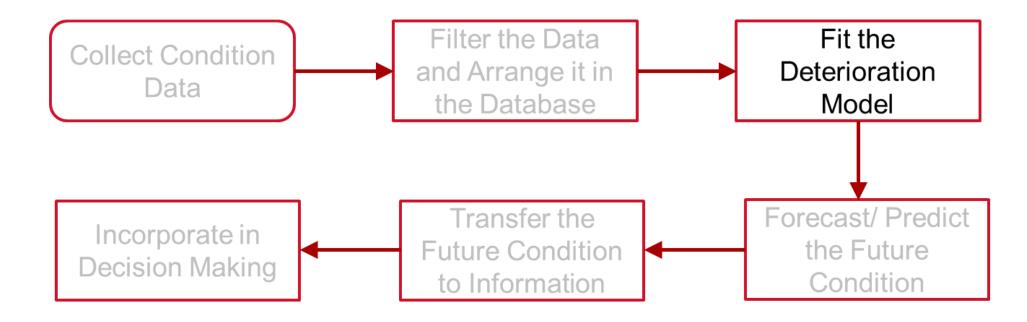


Data can be arranged in a GIS database.



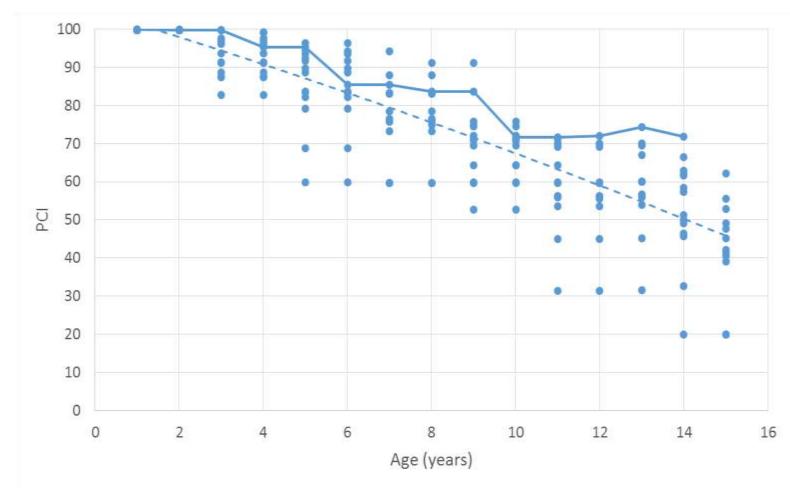


From data collection to decision making.





Performance starts beautiful and becomes ugly.





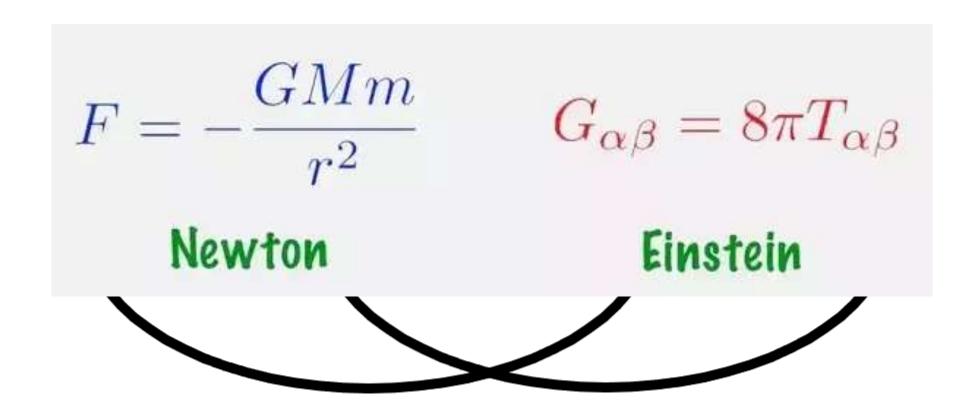
Shopping for models.



https://www.workingmother.com/back-to-school-childrens-fashion-2016



A model can be a law or a theory.



https://en.wikipedia.org/wiki/Scientific_law



What is a model?

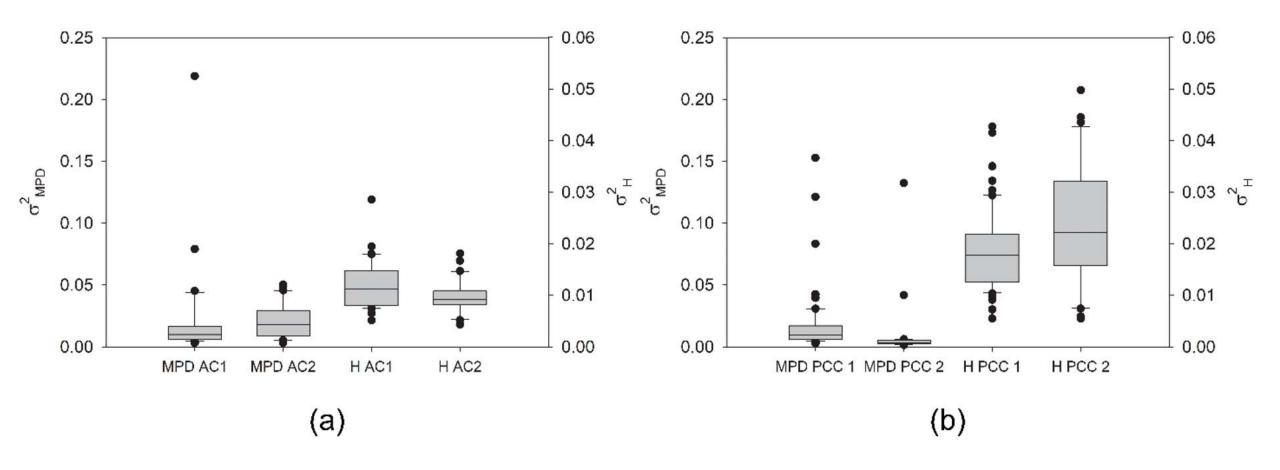
• Mathematically we can define (model) any condition data observation for any asset as a function $f(\mathbf{X}, t)$ with error term ϵ_i :

$$y_i = f(\mathbf{X}, t) + \epsilon_i$$

- Where y_i is the condition record described as a function of multiple independent variables contained in \mathbf{X} at a given time t.
- Many approaches can be used to find the function describing the change in condition over time.

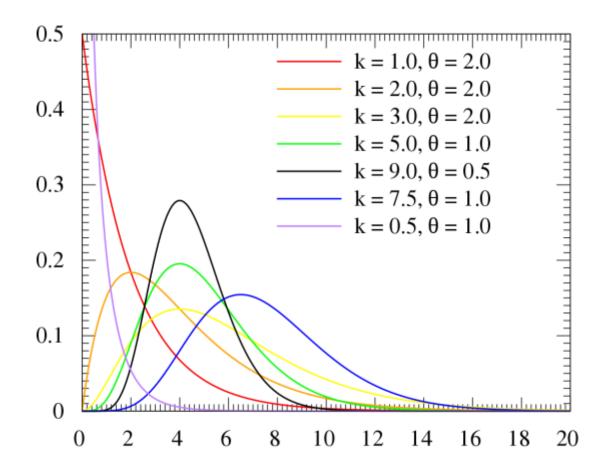


Variability or Uncertainty?!





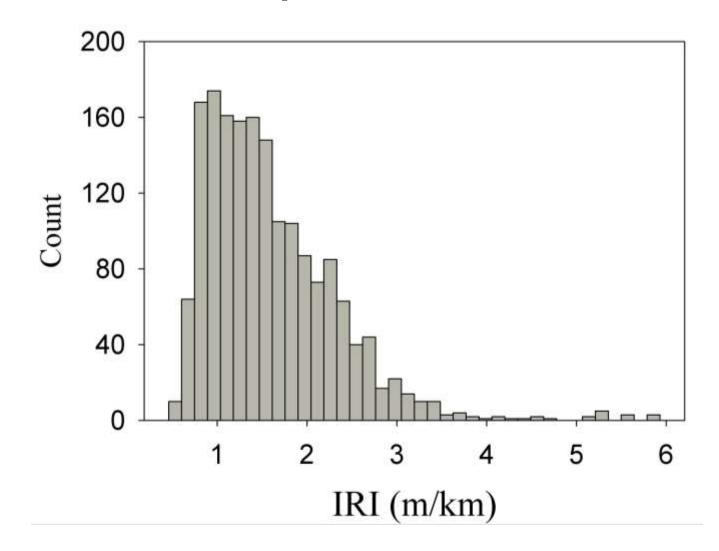
Variability or Uncertainty?!



https://en.wikipedia.org/wiki/Gamma_distribution

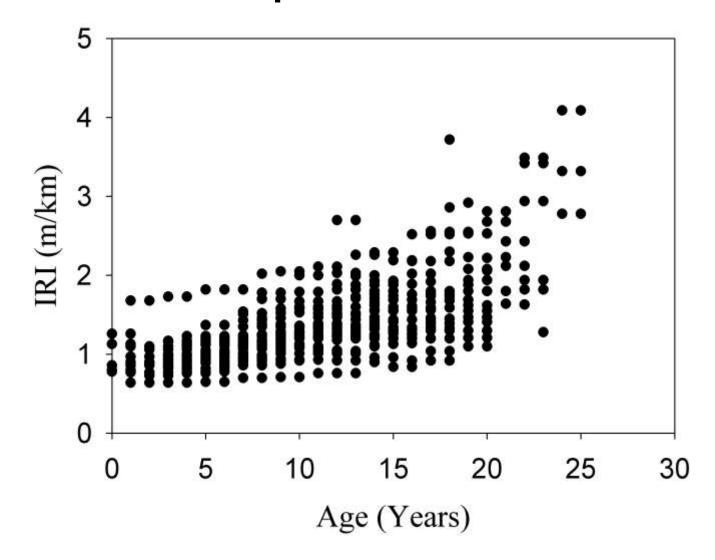


Check the assumptions.



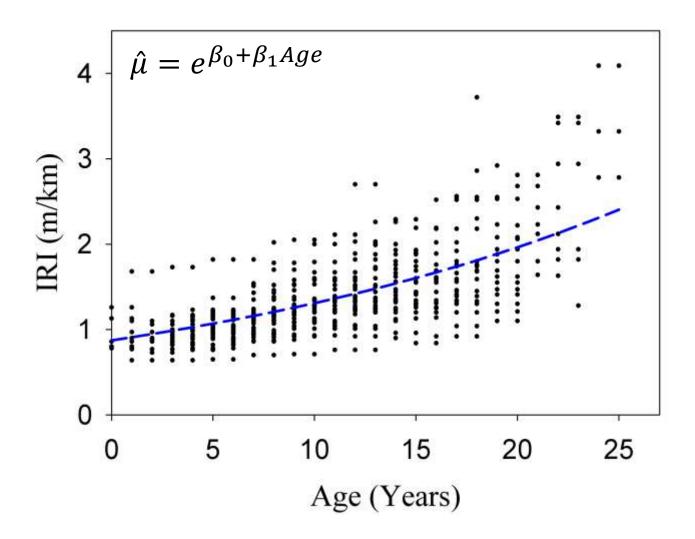


Check the assumptions.





Choose proper regression model.



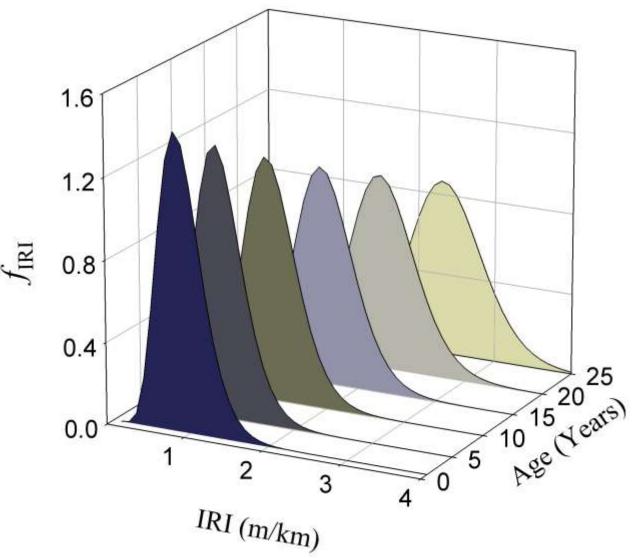


Look deeper.

•
$$f_{IRI} = \frac{IRI^{(\widehat{\mu}/T)-1}e^{-IRI/\varphi}}{\Gamma[\widehat{\mu}/\varphi]\varphi^{\widehat{\mu}/\varphi}}$$

•
$$E[IRI] = \hat{\mu}$$

• $Var(IRI) = \hat{\mu}\varphi$

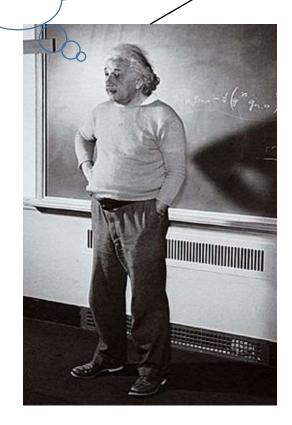


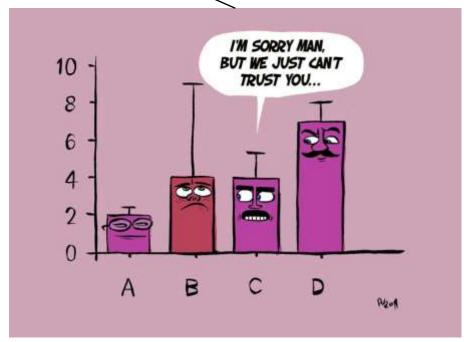


Variability and Uncertainty Decomposition.

Is my model good?!

 $y_i = f(\mathbf{X}, t) + \epsilon_i$

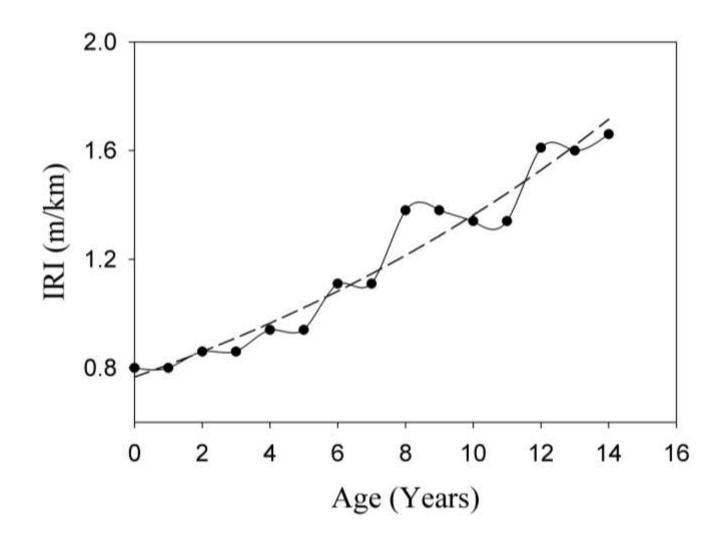




http://berkeleysciencereview.com/importance-uncertainty/

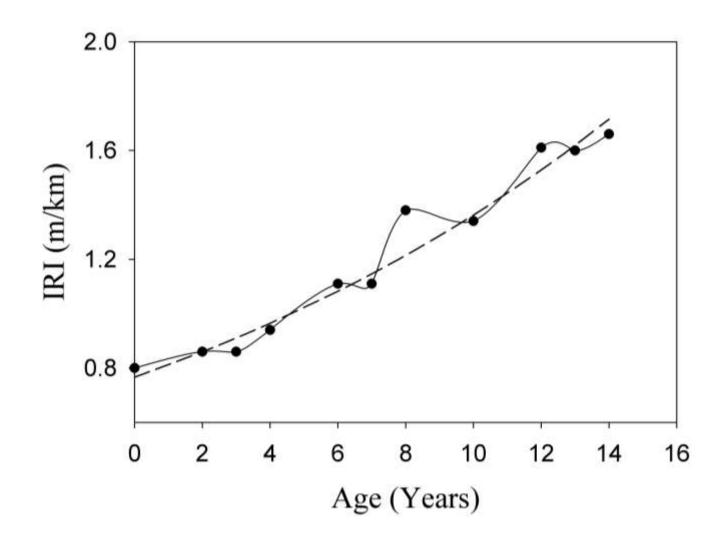


Filtering can make data noisy.



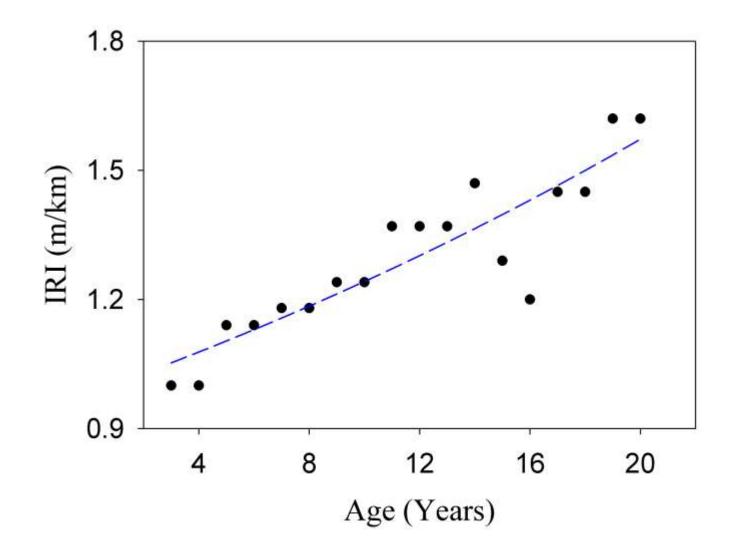


Filtering can make data noisy.





Would cleaner data help?

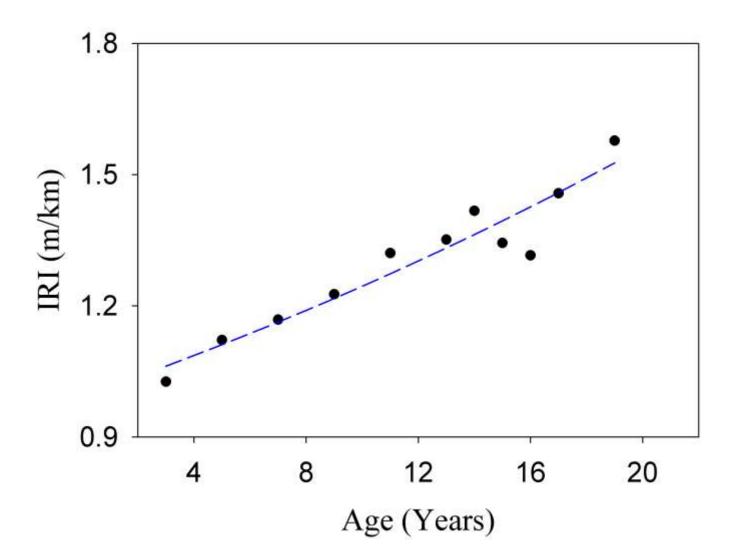




Would cleaner data help?

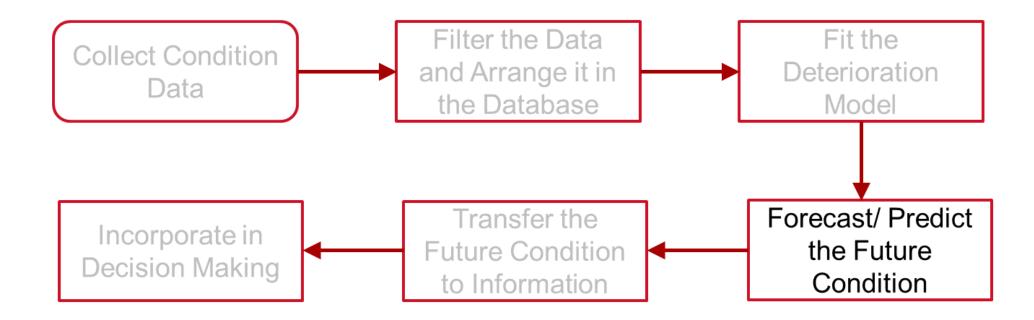
Repeated
measurements
were removed
and the errors
were reduced
by half.

•
$$\sigma^{*2} = (0.5^2)\sigma^2$$



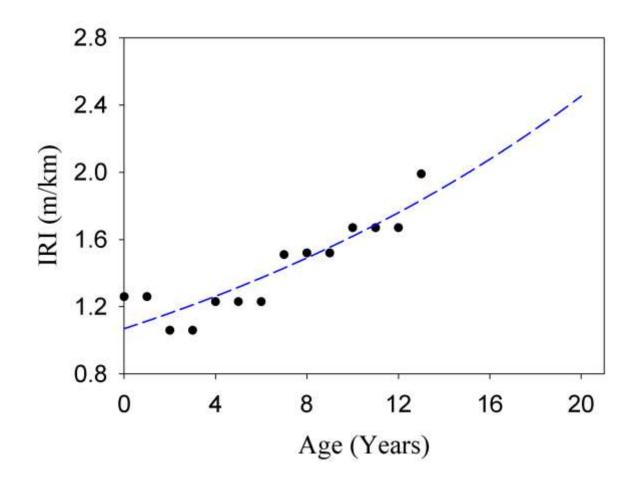


From data collection to decision making.



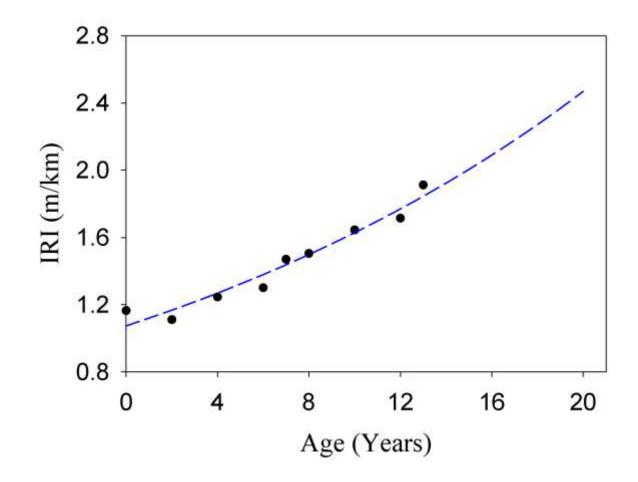


If you know your past you might know your future!



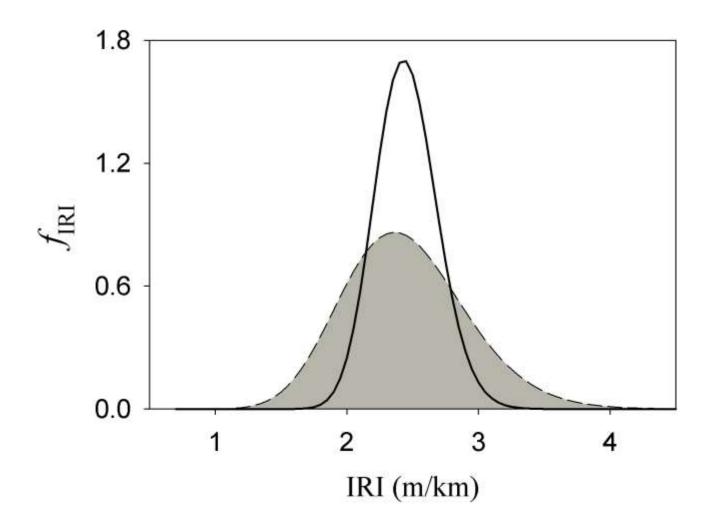


If you know your past you might know your future!



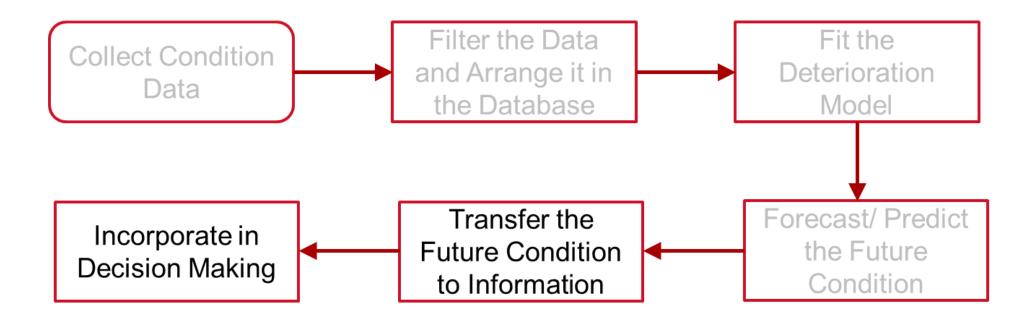


Better data can reduce the uncertainty.



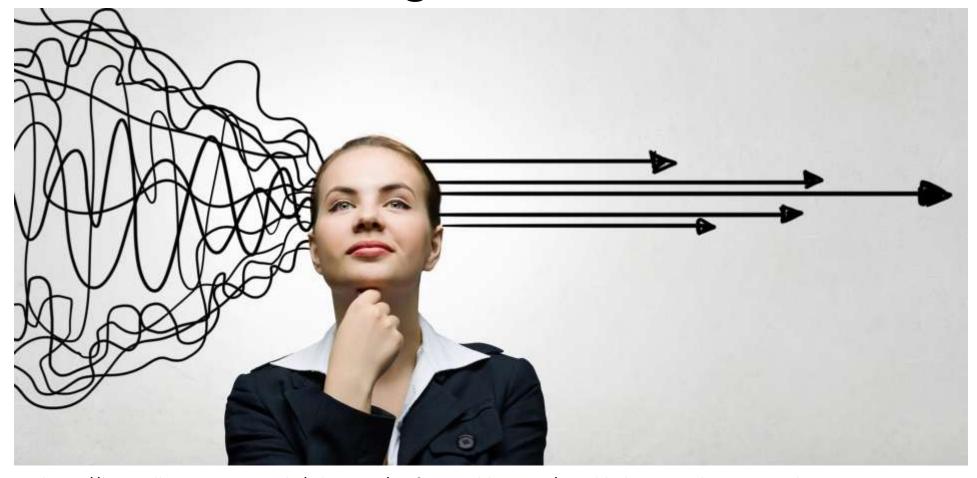


From data collection to decision making.





Data is great but harder to report and use in decision making.



https://www.tilburguniversity.edu/education/professional-learning/sensible-business-decisions-under-uncertainty

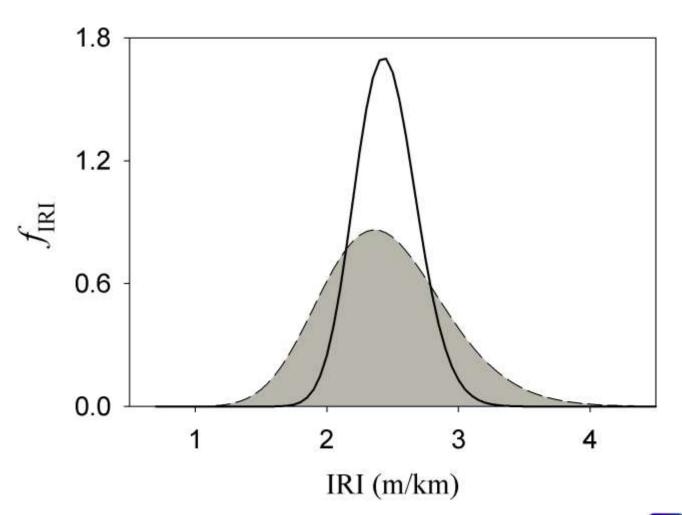


Better data can reduce the uncertainty.

 Both models expect Fair condition.

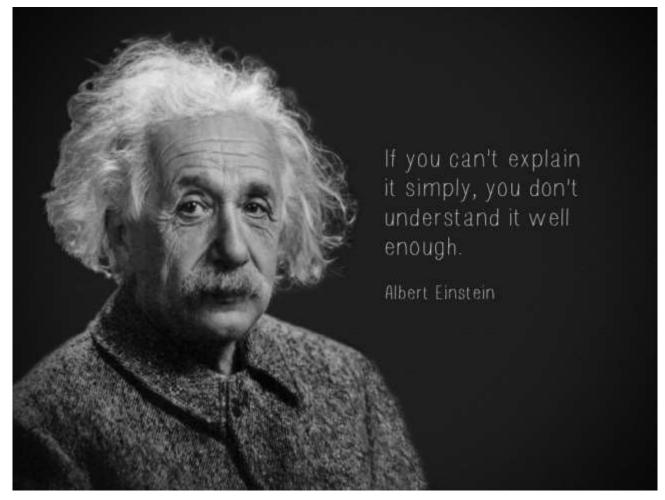
•
$$P_1(C \neq Fair) = 0.3$$

•
$$P_1(C \neq Fair) = 0.15$$





If you are uncertain ask questions





https://projectscreenwriter.com/2017/01/25/loglines-and-a-lot-of-head-scratching/