



Investigation of Applicability and Use of a Pavement Response Model with High Speed Deflection Devices (HSDDs)

Pavement Evaluation 2014 Conference Blacksburg, VA; Sept 2014

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Outline

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Introduction: High Speed Deflection Devices (HSDDs)

- Dynamic Surface Disp. of Response of Layered Systems

Issues: 3D- Viscoelastic Continuum (Vehicle Velocity?) Moving Surface Load (Non-stationary) 3D Loading - Normal and Shear (Breaking?)

Analytical Modeling: 3D-Move

Formulation of a Generalized Analytical Model Material Characterization

Calibration of Analytical Model

- Existing Classical Solutions
 Model Tests _ Lab Calibration
- Field Calibration

Use of 3D-Move to FHWA Network Level Project DTFH61-12-C-00031

- Calibration with Field Measurement (Surface Disp.)
- Calibration with MnROAD Measurements (Stress & Strains)
- Future Work in Sensitivity Studies







Introduction: Pavement Response ame



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Existing Methods: - ELSYM5/WinLEA/JULEA

Static/Stationary/Circular/Uniform, q/ Linear Elastic/Multi-Layer/ "Work Horse"; Developed in 1970s; AASHTO Pavement Design1986 and 2002, 2012 (MEPDG &

Pavement ME)





3D-Move Formulation Finite Layer Approach



Solution for Single Harmonic Pressure It can be shown that U_{nm} is given by: (6th order differential equation)

$$D_1 \frac{d^6 U_{nm}}{dz^6} + D_2 \frac{d^4 U_{nm}}{dz^4} + D_3 \frac{d^2 U_{nm}}{dz^2} + D_4 U_{nm} = 0$$

 $\square D_1, D_2, D_3, \& D_4 = \text{constants that depends on}$

- layer material properties,
- velocity of wave propagation,
- $-\lambda_n$ and μ_m .



Summary: Elements of 3D-Movemer®

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(1) Uses Finite-Layer Continuum Approach – Takes Advantage of Horizontally-Layered Pavement Layers; No Discretization; No Lateral Boundary Effects. – Computer Efficient

(2) Models Moving 3D-Surface Stresses (Dynamic; Normal & Shear Contact Stresses) – Handles Vehicle Speed

(3) Direct Use of Frequency-Sweep Data (Viscoelastic Modeling)

(4) Ideally-Suited when Responses are Needed at a Selected Few Locations - Computer Efficient



- Unbound Materials (?) - Elastic



Dynamic Modulus, |E*|

Master Curve







Comparison Between 3D-Move and ViscoRoute (2.0)



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-20°C ViscoRoute

Ref. 14Vehicle speed, mphBoth Models are: Dynamic and Viscoelastic.

| Important Attribute | 2000 | | | |
|---|---|-----------------------------------|------------------|----------|
| Factor | Layered Elastic Analysis (LEA) e.g.: ELSYM5, WESLEA, JULEA | Finite Element Method (FEM) | 3D-Move Model | dilieu |
| Non-Circular Loaded Shape | NO | YES | YES | 4 |
| Non-Uniform Vertical Contact Stress | NO | YES | YES | |
| Contact Shear Stresses (Braking & Sloping Pavements) | NO | YES | YES | |
| Moving Load (Non- Stationary) and Inertia Included (i.e. Dynamic) | NO | NO/YES | YES | |
| Important Attribute | s of Pavement M | lodeling: Mater | ial Properties | |
| Viscoelastic Properties (Modulus and Phase Shift) | NO | YES | YES | |
| Vehicle Speed | NO | YES | YES | |
| Direct use of Freq. Sweep Data | NO | NO | YES | |



Pavement Responses from 3D-Move Responses: Vertical Disp., HMA strain, Earth Pressure



Use of 3D-Move in FHWA Network Level Project- DTFH61-**AMEC** 12-C-00031

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Focus: High Speed Deflection Devices (HSDDs)

HSDDs: TSD & RWD

Main Goals:

Phase 1: Calibration of 3D-Move using Surface Disp. (UTEP) and with MnROAD Measurements (Stresses & Strains) Three HMA Cells (3, 19 & 34)

Phase 2: Sensitivity Studies: Robust Indicators for Pavement Deterioration



| Cell 3 | | Cell 19 | | |
|--|----------|--|----------|--|
| HMA FWD Modulus = 554 ksi σ = 34 ksi | 3 in | HMA FWD Modulus = 301 ksi σ = 65 ksi | ksi 5 in | |
| Base E = 68.8 ksi σ = 8.5 ksi | 43 in | Base E = 32 ksi σ = 5.8 ksi | 31 in | |
| Subgrade E = 17.7 ksi σ = 2.9 ksi | 122.4 in | Subgrade E = 6.1 ksi σ = 0.6 ksi | 18.1 in | |

Cell 34

| HMA FWD Modulus = 299 ksi σ = 67 ksi | 4 in |
|---|---------|
| Base E = 15.7 ksi σ = 3.1 ksi | 12 in |
| Subgrade E = 8.5 ksi σ = 0.9 ksi | 46.3 in |



Material Characterization: FWD Field Measurements







Backcalculated Stiffnesses of Pavement **Amec Structure**

| Cell | Material | Thickness, in. (cm) | Average Modulus, ksi, (MPa) | Standard Deviation, ksi, (MPa) | Coefficient of Variation (%) |
|------|----------|------------------------|--------------------------------|--------------------------------------|---------------------------------|
| | НМА | 3 (7.6) | 554 (3820) | 34 (234) | 14 |
| 3 | Base | 43 (109.2) | 68.8 (474) | 13.6 (94) | 19.8 |
| | Subgrade | 122.4 (310.9) | 17.7 (122) | 2.2 (15) | 12.3 |
| 19 | НМА | 5 (12.7) | 301 (2075) | 65 (448) | 22 |
| | Base | 31 (78.7) | 32 (221) | 5.8 (40) | 18 |
| | Subgrade | 18.1 (46) | 6.1 (42) | 0.6 (4) | 10.2 |
| 34 | НМА | 4 (10.2) | 299 (2062) | 67 (462) | 22 |
| | Base | 12 (30.5) | 15.7 (108) | 3.1 (21) | 19.9 |
| | Subgrade | 46.3 (117.6) | 8.5 (59) | 0.9 (6) | 10.2 |





- HMA Modulus is sensitive to temp.
- Require Ave. HMA temp. @ time of testing (FWD & HSDDs)
 All FWD and HSDDs Trials "within" 3 Weeks
- Use thermocouple measurements made within HMA (Incomplete data for Cells 19 & 34)
- Use BELLS equation to find appropriate temperature for missing data





| CELL | Temperature at time of FWD, °F (°C) | Temperature at time of TSD, °F (°C) | Temperature at time of RWD, °F (°C) |
|------|---|---|--|
| 3 | 99 (37) | 91 (33) | 99 (37) |
| 19 | 81 (27) | 68 (20) | 63 (17) |
| 34 | 108 (42) | 91 (33) | 90 (32) |



Procedure:

- Backcalculate "Existing" Layer Moduli
 - Use FWD Data (HMA, Base & Subgrade)

All FWD and HSDDs Trials "within" 3 Weeks

Use Wictzack Equn. to find Master Curve for HMA Modulus (Temp. & Freq.)

- Note: f_{FWD} = 30Hz; Use FWD Test Temp.

Parameters needed for the dynamic modulus predictive equation are:

- Air void content.
- Asphalt content.
- Gradation.
- A & VTS for the recovered binder.

Undamaged Master Curve

Obtaining Damaged/Existing Modulus: Witczak Equn.

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ame





Master Curve - Cell 34





| Cell | HSDD | Passes | Velocity |
|---------|------|----------|-------------------|
| Cell 3 | TSD | 3 Passes | 48, 72 km/h |
| | RWD | 3 Passes | 48, 72, & 97 km/h |
| | CRV | 3 Passes | 17.6 km/h |
| Cell 19 | TSD | 3 Passes | 48, 72, & 97 km/h |
| | RWD | 3 Passes | 48, 72, & 97 km/h |
| | CRV | 3 Passes | 17.6 km/h |
| Cell 34 | TSD | 3 Passes | 48 & 72 km/h |
| | RWD | 3 Passes | 48 & 72 km/h |
| | CRV | 3 Passes | 17.6 km/h |

Total: 15 Cases (TSD & RWD) + 3 Cases (CRV)



TSD Loading and UTEP Instruments











NOTE: Ideally GEO1 & GEO3 should yield same results (Indication of variability) For 3D-Move Calibration use Highest UTEP Geophone Disp. Sensor Measurements (i.e., GEO3)







Locate sensor behind wheel, when looking for w_{max}

N

Looking for Maximum Displacement (Transverse Plane)













Role of Variation in Tire Load in **Amec** TSD

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Dynamic wheel loads: Testing@BASt



5 axle truck-semitrailer - 40 t gross weight - winding country road - v ~40-50 km/h

bast

NOTE: Uneven Load Distribution within Axle











3D-Move Case Scenarios

Case 1: Three layer pavement structure with same thicknesses as used in the FWD backcalculation and corresponding mean layer moduli derived from the FWD backcalculation results;

Case X: Three layer pavement with: (a) thicknesses used in the FWD backcalculation except decreasing the HMA layer thickness by 1 in, (b) (mean $-\sigma$) of FWD backcalculated layer moduli for HMA and base layers, (c) (mean $+\sigma$) of FWD backcalculated layer moduli for subgrade, and (d) +25% of nominal tire load;

Case X1: Same as Case X, but with no reduction in HMA layer thickness.













Computed vs Measured Maximum Displacements



15 Datasets (TSD & RWD)





Computed vs Measured Pulse Width

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Measured Pulse Width /(Project Sensors) (ft)

45 Datasets (TSD & RWD)





Vertical Earth Pressures and Long. Strains in HMA

Issues: Lateral wheel wander Size of sensors









Computed and Measured Longitudinal Strains ameconic in TSD Trials





monted and Measured Normal Pressure in RwBtriae













Maximum longitudinal strains from **a** MnROAD sensors and 3D-Move computations





Use of 3D-Move in FHWA Network Level Project- AMEC DTFH61-12-C-00031

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Phase 2: What are the Robust Indicators that can Capture HMA Deterioration?

Following Issues are to be Investigated by 3D-Move Solutions:

(1) What is the sensitivity of measured deflections in HSDDs with respect to: (a) speed of test vehicle; (b) change in material properties of all pavement layers (i.e., temperature, aging and moisture related stiffness changes); and (c) sloping pavements (require inclusion of interface shear);

(2) Are there any other pavement response parameters that may be sensitive to pavement condition? For example, can the velocities measured in TSD be directly used as indicators, instead of relying on displacement bowl obtained using the slopes at a few locations (potentially introducing errors) recognizing that the focus is on surface bound layer;





(3) **3D-Move analyses to understand best way to implement devices** *a) What are the ideal locations for measurements (e.g., between the tires, in front or back of the tires)*

b) Are there any pavement response parameters other than the deflection between tires (RWD) and SCI 300 (TSD) that may be sensitive to pavement condition?

c) Are there any indices that can be used where the existing measurements made by HSDDs can be utilized? (e.g., w_o, SCI300, Thompson: $(5D_0 - 2D_{12"} - 2D_{24"} - D_{36"})/2$; BCI = $D_{24"} - D_{36"}$; SD = tan⁻¹ ($D_0 - D_r$)/r etc.)

(4) What are the "error" margins when periodically measured HSDD responses obtained at various times of a year during the life of a pavement are compared?

This is important, when looking for progressive deterioration of pavement.





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